

OpenKC - Feature #1

Add Support for Impedance Control Modes

2010-06-15 10:50 - Matthias Schöpfer

<b>Status:</b>	Closed	<b>Start date:</b>	2010-06-15
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	Matthias Schöpfer	<b>% Done:</b>	100%
<b>Category:</b>		<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>		<b>Spent time:</b>	108.00 hours
<b>Description</b>			
Only Controller available under FRI is right now Position Control Add possibilities to change to Impedance Control modes			

History

#1 - 2010-07-06 12:26 - Matthias Schöpfer

- Status changed from New to In Progress
- Assignee set to Matthias Schöpfer
- % Done changed from 0 to 70

Waiting on message from Kuka if FRI\_CMD\_JNTPOS | FRI\_CMD\_CARTPOS is possible after all.

#2 - 2010-10-18 15:39 - Matthias Schöpfer

- Status changed from In Progress to Resolved
- % Done changed from 70 to 100

Finally, thanks to Michael Gerung from Kuka Roboter GmbH, we were able to resolv this issue!

#3 - 2011-06-10 10:48 - Matthias Schöpfer

- Status changed from Resolved to Closed